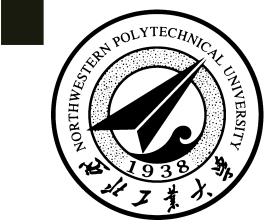
Enabling Quality Control for Entity Resolution: A Human and Machine Cooperation Framework

Zhaoqiang Chen, <u>Qun Chen</u>, Fengfeng Fan, Yanyan Wang, Zhuo Wang, Youcef Nafa, Zhanhuai Li, Hailong Liu, Wei Pan



Northwestern Polytechnical University

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- Background
- Motivation
- The HUMO Framework
- Optimization Approaches
- Experiments
- Conclusion

Background

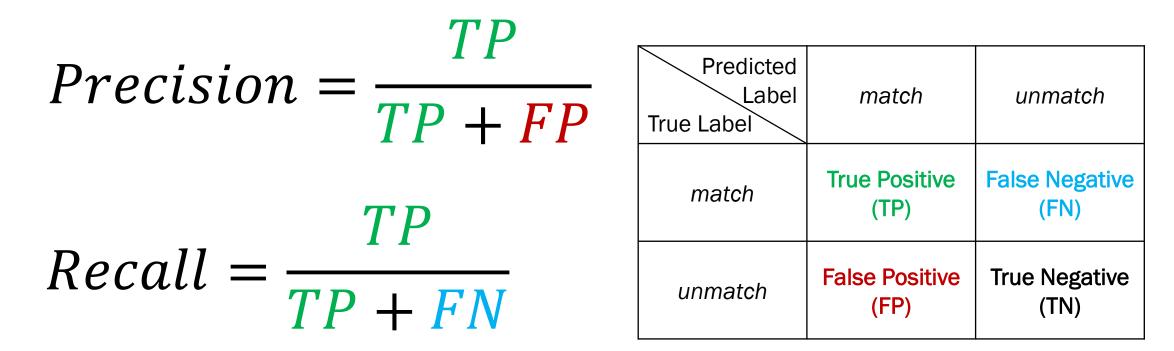
Entity Resolution (**ER**): Identify the relational records that correspond to the same real-world entity.

Data source 1:



Background

Measurement on the *Quality* of an ER solution:



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Motivation

Pure machine-based ER solutions usually struggle in ensuring desired quality guarantees specified at both *precision* and *recall* fronts.



Precision \geq The requirement? and Recall \geq The requirement?

Motivation

| ER Techniques | Quality Guarantees | |
|--|--------------------|--------------|
| | Precision | Recall |
| Rules, Probabilistic Theory or Machine Learning based | X | × |
| Active-learning based [1][2] | \checkmark | × |
| HUMO | \checkmark | \checkmark |

Difference: cannot enforce comprehensive quality guarantees specified by both precision and recall metrics as HUMO does.

[1] A. Arasu, M. Gotz, et al. On active learning of record matching packages. SIGMOD 2010.[2] K. Bellare, S. Iyengar, et al. Active Sampling for entity matching. SIGKDD 2012.

[1] Learns record matching packages such that $Precision \geq Threshold$ Similarity Dim F2 0.5 00 0.0 0.5 1.0 Similarity Dim F1

EnumerateBoundary^[1]

Motivation

Humans usually perform better than machines in terms of quality, but human labor is much more expensive.

Therefore, HUMO has been designed with the purpose of minimizing human cost given a particular quality requirement.

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- Suppose that each instance pair can be evaluated by a machine metric.
 - Pair similarity
 - Classification metrics, e.g., match probability and Support Vector Machine distance.
- For simplicity of presentation, we use pair similarity as a machine metric example in this work. *However, HUMO is similarly effective with other machine metrics.*

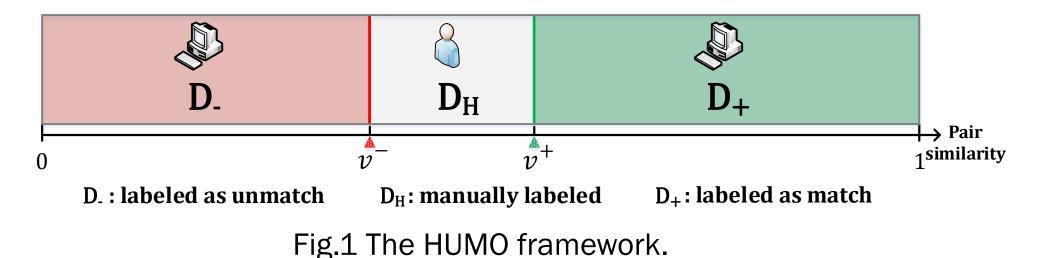
Assumption [Monotonicity of Precision*]:

For any two value intervals $I_i \leq I_j$ in [0, 1], we have $R(I_i) \leq R(I_j)$, in which $R(I_i)$ denotes the precision of the set of instance pairs whose metric values are located in I_i .

The higher (resp. lower) metric values a set of pairs have, the more probably they are matching pairs (resp. unmatching pairs).

* It was first proposed by A. Arasu, M. Gotz, et al. On active learning of record matching packages. SIGMOD 2010.



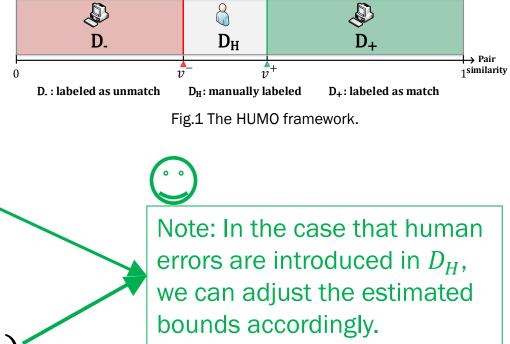


Given a HUMO solution *S*, the lower bound of its achieved precision and recall can be represented by,

of matches

 $Precision_{l}(S) = \frac{1}{2}$

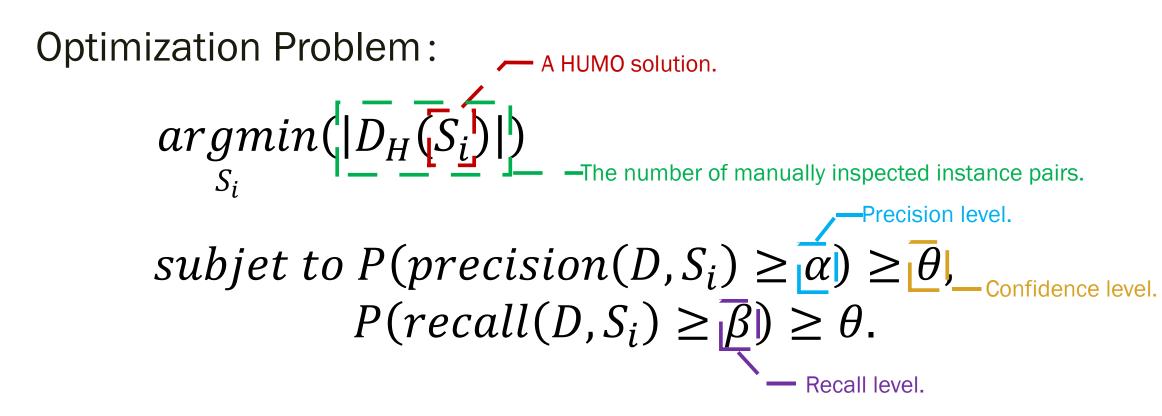
Lower bound



 $\operatorname{Recall}_{l}(S) = \frac{N_{l}^{+}(D_{+}) + N_{l}^{+}(D_{H})}{N_{l}^{+}(D_{+}) + N_{l}^{+}(D_{H}) + N_{u}^{+}(D_{-})}$ Upper bound

In this paper, we assume that the pairs in D_H can be manually labeled accurately.

 $= \frac{N_l^+(D_+) + N_l^+(D_H)}{N(D_+) + N(D_H)}$



The problem of searching for the minimum size D_H is challenging due to the fact that the ground-truth match proportions of D_- and D_+ are unknown.

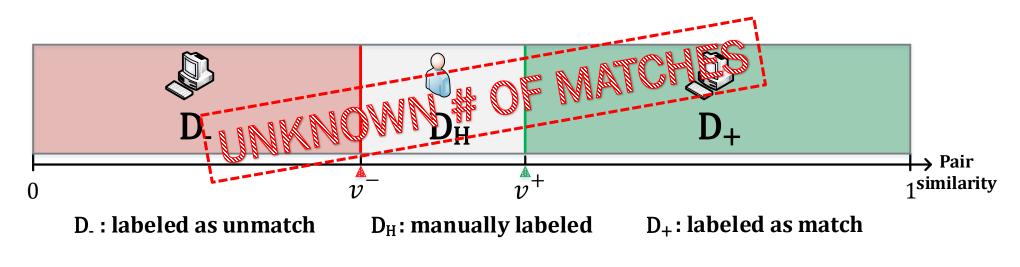
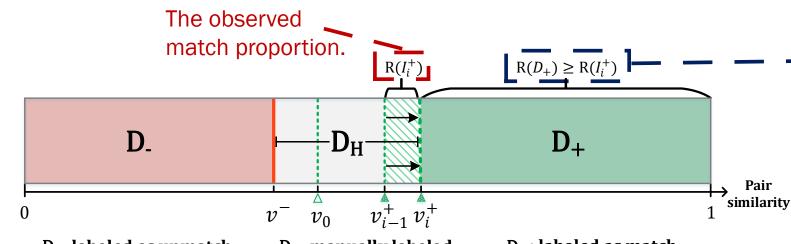


Fig.1 The HUMO framework.

Outline

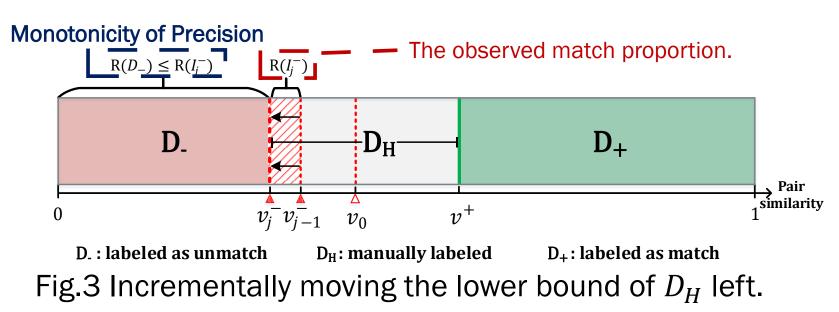
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 - Sampling-based approach
 - Hybrid approach
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Baseline Approach



Monotonicity of Precision: the more similar two records are, the more likely they refer to the same real-world entity.

D.: labeled as unmatch D_{H} : manually labeled D_{+} : labeled as match Fig.2 Incrementally moving the upper bound of D_{H} right.



Baseline Approach

The precision requirement α and recall requirement β would be satisfied once:

$$R(I_{i}^{+}) \geq \frac{\alpha \cdot |D_{+}| - (1 - \alpha) \cdot R(D_{H}) \cdot |D_{H}|}{|D_{+}|}$$
$$R(I_{j}^{-}) \leq \frac{(1 - \beta) \cdot (|D_{H}| \cdot R(D_{H}) + |D_{+}| \cdot R(I_{i}^{+}))}{\beta \cdot |D_{-}|}$$

However:

- It may *underestimate* the match proportion of D_+ .
- It may **overestimate** the match proportion of *D*_.

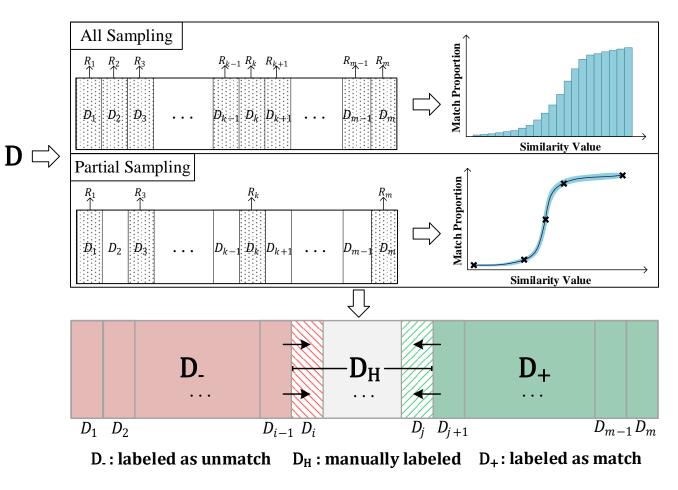


Fig.4 The demonstration of sampling-based solution.

All-Sampling Solution:

- Stratified Random Sampling.
- Sample every subset → human cost consumed on labeling samples is usually prohibitive.

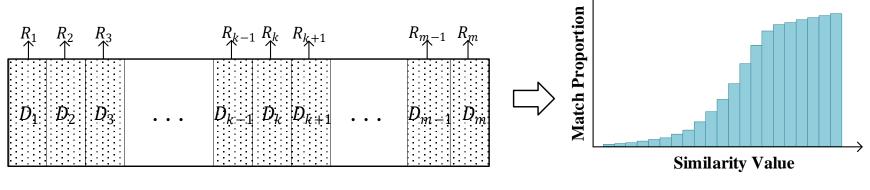


Fig.5 All-sampling solution.

Partial-Sampling Solution:

- Gaussian Process Regression.
- The match proportions of subsets have a joint Gaussian distribution.

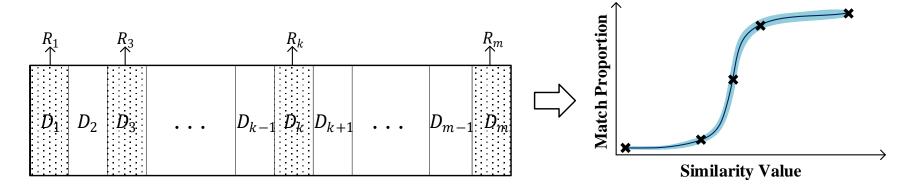
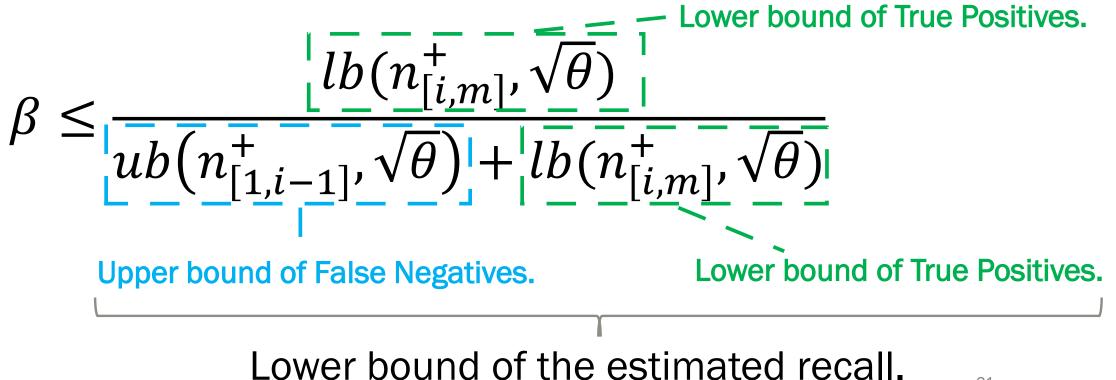
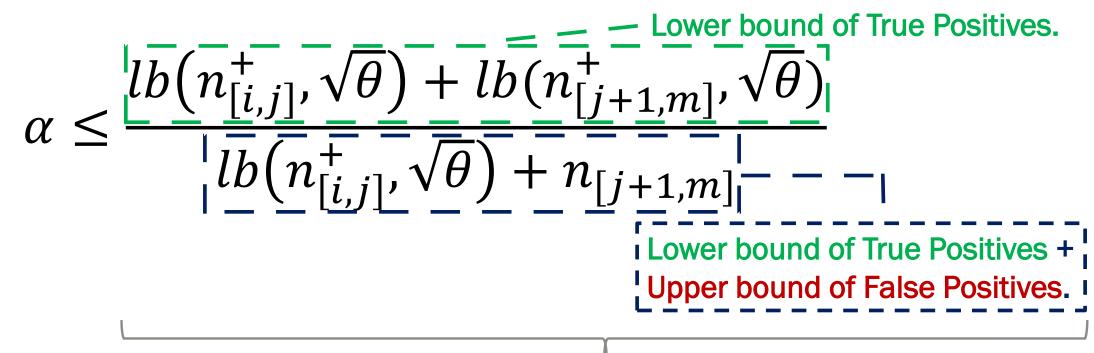


Fig.6 Partial-sampling solution.

Given the confidence level θ and the **recall level** β , the HUMO solution meets the recall requirement if:



Given the confidence level θ and the **precision level** α , the HUMO solution meets the precision requirement if:



Lower bound of the estimated precision.

Hybrid Approach

The baseline approach

- -- overestimates the match proportion of *D*_;
- -- underestimates the match proportion of D_+ .

> The sampling-based approach

-- has to consider confidence margins in the estimations of D_{-} and D_{+} .

-- has large error margins when sample size is small.

Hybrid Approach

- Takes advantage of both estimations and uses the better of both worlds in the process of bound computation.
 - Begins with an initial solution of the partialsampling approach, S_0 , and its lower and upper bounds of D_H ;
 - Incrementally redefines D_H 's bounds using the better between the baseline and sampling-based estimates.

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Experiments

• Datasets: DBLP–Scholar^[1] (abbr. DS); Abt–Buy^[2] (abbr. AB); Synthetic Datasets.

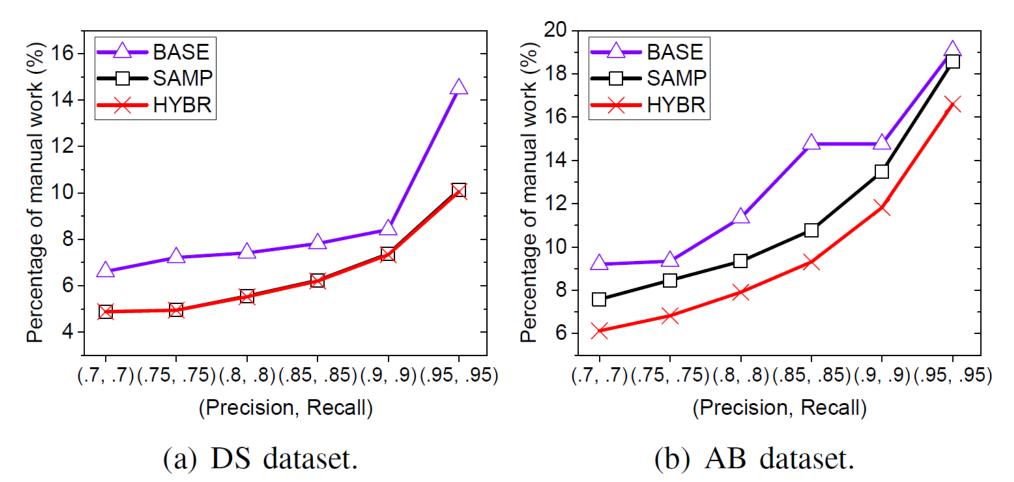


Fig.7 Comparison of human cost on two real datasets (with confidence set to 0.9).

Baseline approach requires lesser manual work than Sampling-based one.

Hybrid approach can effectively use the better of both BASE and SAMP estimates.

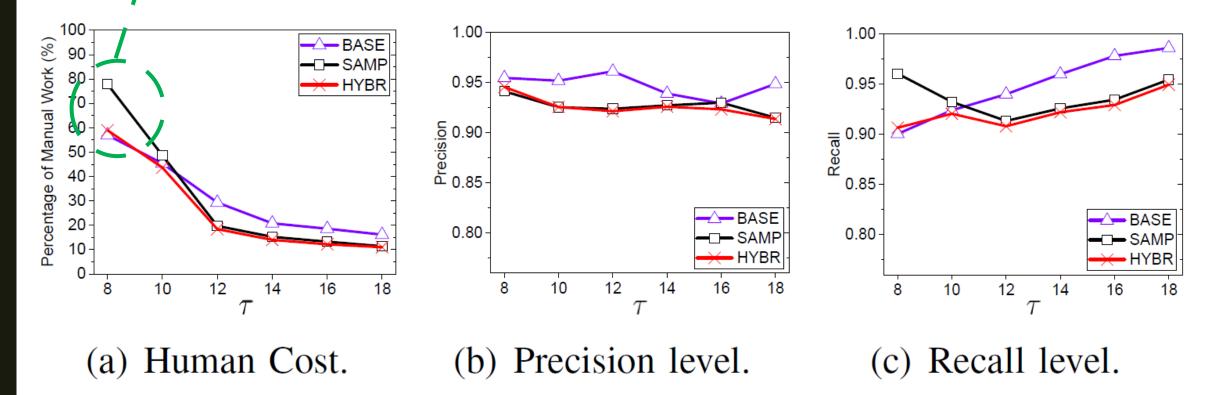
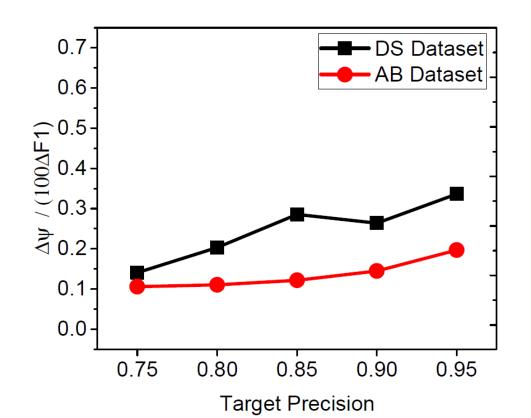


Fig.8 Varying τ (steepness) of the logistic curve on the synthetic datasets.

Note: The smaller the value of τ is, the more challenging the generated ER workload would be.

Active learning-based approaches [1], [2] have been proposed in order to satisfy the precision requirement for ER.



HUMO can effectively improve the resolution quality with reasonable return on investment in terms of human cost.

Fig.9 The percentage of manual work incurred by HUMO for 1% absolute improvement in F1 score over $ACTL^{[1]}$.

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Conclusion

- A human and machine cooperation framework for ER.
- It enables a flexible mechanism for comprehensive quality control at both precision and recall levels.
- Three optimization approaches to minimize human cost given a quality requirement.

Future Work

 Integrate HUMO into existing crowdsourcing platforms.

 As a general paradigm, HUMO can be potentially applied to other challenging classification tasks requiring high quality guarantees (e.g., financial fraud detection and malware detection).

Thank you ! Q&A